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Spectral geometry in a rotating frame: properties of the ground state

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joint work with Pavel Exner

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We consider the spectral properties of the operator (formally) defined by

$$H_{\omega}(x_0, y_0) = -\Delta + i\omega \left((x - x_0)\partial_y - (y - y_0)\partial_x \right)$$

on $\Omega\subset\mathbb{R}^2$ subject to the Dirichlet boundary conditions. Here $\omega>0,\quad (x_0,y_0)\in\mathbb{R}^2.$

Physical motivations

The above operator describes a quantum particle confined to a planar domain Ω rotating around a fixed point with an angular velocity ω . Quantum effects associated with rotation attracted a particular attention in connection with properties of ultracold gases.

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$$\omega > \mathbf{0}, \quad (\mathbf{x}_0, \mathbf{y}_0) \in \mathbb{R}^2.$$

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Associated quadratic form

For any $u \in C_0^\infty(\Omega)$ one has

$$(H_{\omega}(x_0, y_0)u, u)_{L^2(\Omega)} = \int_{\Omega} \left| i\nabla u + \widehat{A}u \right|^2 \mathrm{d}x \,\mathrm{d}y - \frac{\omega^2}{4} \int_{\Omega} ((x - x_0)^2 + (y - y_0)^2) |u|^2 \,\mathrm{d}x \,\mathrm{d}y,$$

where
$$\widehat{A} = (-y + y_0, x - x_0)$$
.

Boundedness of Ω implies that the corresponding operator is bounded from below, hence it allows for Friedrichs extension

$$\widehat{H}_{\omega}(x_0, y_0) = \left(i\nabla + \frac{\omega}{2}\widehat{A}\right)^2 - \frac{\omega^2}{4}\left((x - x_0)^2 + (y - y_0)^2\right)$$

with the domain $\mathcal{H}^2(\Omega) \cap \mathcal{H}^1_0(\Omega)$.

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Remark

By simple gauge transformation, namely

 $u(x,y)\mapsto u(x,y)\mathrm{e}^{-i\omega(xy_0-yx_0)/2},$

the operator $\widehat{H}_{\omega}(x_0, y_0)$ is unitarily equivalent to

$$\widetilde{H}_{\omega}(x_0, y_0) = \left(i\nabla + \frac{\omega}{2}A\right)^2 - \frac{\omega^2}{4}\left((x - x_0)^2 + (y - y_0)^2\right)$$

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with A := (-y, x).

The spectrum of $\widetilde{H}_{\omega}(x_0, y_0)$ is purely discrete.

The main object of interest in the talk

Our concern will be **the principal eigenvalue** $\lambda_1^{\omega}(x_0, y_0)$ of $\widetilde{H}_{\omega}(x_0, y_0)$.

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The first problem concerns

$(\textbf{\textit{x}}_0,\textbf{\textit{y}}_0)\mapsto\lambda_1^\omega(\textbf{\textit{x}}_0,\textbf{\textit{y}}_0)$

for **fixed** Ω and ω , in particular, the existence of its extrema.

Theorem (B.-Exner, 2019)

 $\lambda_1^\omega(\cdot,\cdot)$ as a map $\mathbb{R}^2\to\mathbb{R}$ has no minima. It has a unique maximum.

Remark

 $\lambda_1^{\omega}(x_0, y_0) \to -\infty$ holds as $(x_0, y_0) \to \infty$. This guarantees the existence of maxima.

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Sketch of the proof

Let (x_0, y_0) be a possible extrema point.

Step 1

We employ normalized eigenfunctions $u_{\omega}^{(x_0,y_0)}$ and $v_{\omega}^{(x_0,y_0)}$ corresponding to $\lambda_1^{\omega}(x_0,y_0)$ such that

$$\begin{split} & u_{\omega}^{(x_0+t,y_0)} = u_{\omega}^{(x_0,y_0)} + \mathcal{O}(t), \\ & v_{\omega}^{(x_0,y_0+s)} = v_{\omega}^{(x_0,y_0)} + \mathcal{O}(s), \end{split}$$

for small values of *t* and *s*, where the error term is understood in the L^{∞} sense.

The existence of such eigenfunctions is due to

[N. Raymond: Bound States of the Magnetic Schrödinger Operators, EMS, 2017]

If the eigenvalue $\lambda_1^{\omega}(x_0, y_0)$ is simple then $u_{\omega}^{(x_0, y_0)} = v_{\omega}^{(x_0, y_0)}$. In fact we shall see that this not true in general.

Introduction Existence and uniqueness of maximum, absence of minimums Optimalization of the ground state eigenvalue Optimization with respect to ω Domain comparison Step 2 The key point – to prove the following implication: (x_0, y_0) is an extremum point ∜ $\int_{\Omega} (x - x_0) |u_{\omega}^{(x_0, y_0)}|^2 \, \mathrm{d}x \, \mathrm{d}y = 0 \quad \text{and} \quad \int_{\Omega} (y - y_0) |v_{\omega}^{(x_0, y_0)}|^2 \, \mathrm{d}x \, \mathrm{d}y = 0$

Also, using min-max principle, one can deduce for small t > 0 $\lambda_1^{\omega}(x_0, y_0) < \lambda_1^{\omega}(x_0 + t, y_0)$. **Contradiction** (since (x_0, y_0) is an extremum).

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Step 2
The key point – to prove the following implication:

$$(x_0, y_0)$$
 is an extremum point
 \downarrow
 $\int_{\Omega} (x - x_0) |u_{\omega}^{(x_0, y_0)}|^2 dx dy = 0$ and $\int_{\Omega} (y - y_0) |v_{\omega}^{(x_0, y_0)}|^2 dx dy = 0$

Idea of its proof: assume that this in not true, for example, one has

$$\int_{\Omega} (x-x_0) \, |u_{\omega}^{(x_0,y_0)}|^2 \, \mathrm{d}x \, \mathrm{d}y > 0.$$

Using min-max principle, one can show that the above inequality implies for any h < 0 small enough $\lambda_1^{\omega}(x_0 + h, y_0) < \lambda_1^{\omega}(x_0, y_0)$.

Also, using min-max principle, one can deduce for small t > 0 $\lambda_1^{\omega}(x_0, y_0) < \lambda_1^{\omega}(x_0 + t, y_0).$

Contradiction (since (x_0, y_0) is an extremum).

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Step 3

Using (cf. Step 2)

$$\int_{\Omega} (x - x_0) |u_{\omega}^{(x_0, y_0)}|^2 \, \mathrm{d}x \, \mathrm{d}y = 0, \quad \int_{\Omega} (y - y_0) |v_{\omega}^{(x_0, y_0)}|^2 \, \mathrm{d}x \, \mathrm{d}y = 0$$

and min-max principle one can prove that for all nonzero and sufficiently small \boldsymbol{h}

$$\lambda_1^{\omega}(\mathbf{x}_0 + \mathbf{h}, \mathbf{y}_0) < \lambda_1^{\omega}(\mathbf{x}_0, \mathbf{y}_0).$$

Thus (x_0, y_0) is a point of maximum.

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Theorem (B.-Exner, 2019)

Let Ω be convex, then

$(\textbf{\textit{x}}_0,\textbf{\textit{y}}_0)\mapsto\lambda_1^\omega(\textbf{\textit{x}}_0,\textbf{\textit{y}}_0)$

reaches its maximum at a point belonging to Ω .

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If ω is **small** then the position of the maximum can be described more precisely.

Definition

Given a region $\Sigma \subset \mathbb{R}^2$ and a line *P*, we denote by Σ^P the mirror image of Σ with respect to *P*.

Theorem (B.-Exner, 2019)

Let Ω be convex set and P be a line which divides Ω into two parts, Ω_1 and Ω_2 , in such a way that $\Omega_1^P \subset \Omega_2$. Then for small enough values of ω the point at which $\lambda_1^{\omega}(x_0, y_0)$ attains its maximum does not belong to Ω_1 .

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Sketch of the proof

Recall: $H_{\omega}(x_0, y_0) = -\Delta_D^{\Omega} + i\omega((x - x_0)\partial_y - (y - y_0)\partial_x).$

Without loss of generality we may suppose that *P* is parallel to the *Y* axis. Let $(x_0, y_0) \in \Omega_1$ and assume that *P* passes through it.

Consider first the case $\omega = 0$. Let u_D be the ground state eigenfunction of the Dirichlet Laplacian,

 $-\Delta_{\Omega}^{D}u_{D}=\lambda_{1}^{D}u_{D}.$

In view of standard perturbation theory for all sufficiently small ω the ground state eigenvalue $\lambda_1^{\omega}(x_0, y_0)$ is simple and the corresponding eigenfunction satisfies

 $u^{\omega}(x_0,y_0)(x,y)=u_D(x,y)+\mathcal{O}(\omega).$

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Key lemma

$$\int_{\Omega} (x-x_0)(u_D(x,y))^2 \,\mathrm{d}x \,\mathrm{d}y > 0.$$

Proof: later.

Using the above lemma we conclude (since $\|u^{\omega}(x_0, y_0) - u_D\|_{L^{\infty}} \ll 1$)

$$\int_{\Omega}(x-x_0)(u^{\omega}(x_0,y_0)(x,y))^2\,\mathrm{d}x\,\mathrm{d}y>0.$$

But this contradicts to the neccesary condition for the point (x_0, y_0) to be a point of maximum.

Recall

The necessary condition for the maximum is $\int_{\Omega} (x - x_0) (u^{\omega}(x_0, y_0)(x, y))^2 dx dy = 0$.

Thus (x_0, y_0) is not a point of maximum. It remains to prove the above lemma.

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Proof of Lemma

$$v(x,y) := u_D(x,y) - u_D(x^P,y)$$
 on Ω_1 ,

where (x^{P}, y) is the mirror image of (x, y) with respect to *P*.

Positivity of u_D implies

$$v|_{\partial\Omega_1}\leq 0.$$

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• $v|_{\partial\Omega_1} \leq 0$

- $-\Delta v = \lambda_1^D v$ on Ω_1
- the maximum principle for the second order elliptic partial differential equations



Our next topic is to compare the ground state eigenvalue of $H_{\omega}(x_0, y_0)$ with **different values** of ω .

Theorem (B.-Exner, 2019)

$\lambda_1^{\omega}(\mathbf{x}_0, \mathbf{y}_0) \leq \lambda_1^D(\Omega),$

where $\lambda_1^D(\Omega)$ is the ground state eigenvalue of the Dirichlet Laplacian $-\Delta_D^{\Omega}$ on Ω .

Moreover, the inequality is sharp for $\omega > 0$ provided the region Ω does not have full rotational symmetry (disk or a circular annulus with (x_0 , y_0) being its center).

Let us now look more closely at the situation when the system has a rotational symmetry.

Hereafter in this subsection Ω is a **disk** of radius *R* rotating around its center which we identify with the point (0, 0).

In this case the spectrum is

$$\lambda_{m,k}(R,\omega) = rac{j_{m,k}^2}{R^2} - m\omega, \quad m \in \mathbb{Z}, \ k \in \mathbb{N},$$

where $j_{m,k}$ is the *k*th positive zero of Bessel function of the first kind J_m .

$$\lambda_1^{\omega}(x_0, y_0) = \inf_{m,k} \lambda_{m,k} = \inf_{m \ge 0} \lambda_{m,1}$$

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Example of a disk

Lemma

For each $m \in \mathbb{N}$ there is positive $\omega_0 > 0$ such that

$$\lambda_{m,1} \ge \frac{j_{0,1}^2}{R^2}, \quad \omega \le \omega_0.$$

Remark

$$\frac{j_{0,1}^2}{R^2} = \lambda_1^D(\Omega).$$

Theorem (B.-Exner, 2019)

 $\lambda_1^{\omega}(x_0, y_0) \leq \lambda_1^D(\Omega).$

Corollary (Theorem + Lemma + Remark)

 $\lambda_1^{\omega}(\mathbf{x}_0,\mathbf{y}_0) = \lambda_1^D(\Omega), \quad \omega \in (\mathbf{0},\omega_0].$

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Remark

The ground state eigenvalue of $\widetilde{H}_{\omega}(0,0)$ becomes degenerate for some ω , for example



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$$\omega = \frac{j_{1,1}^2 - j_{0,1}^2}{R^2}.$$

In the last part of the talk we demonstrate an estimate in which the ground state eigenvalue is compared to that of a disk of the same area.

For this purpose we add the index specifying the region writing $\widetilde{H}_{\omega,\Omega}(x_0, y_0)$ and $\lambda_{1,\Omega}^{\omega}(x_0, y_0)$.

We restrict our attention to convex regions with a fixed $(x_0, y_0) \in \Omega$ which we can write as

 $\Omega = \left\{ (x_0 + r\cos\varphi, y_0 + r\sin\varphi) : \varphi \in [0, 2\pi), \ r \in [0, R(\varphi)) \right\}$

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for a suitable 2π -periodic function *R*.

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for a suitable 2π -periodic function *R*.

Theorem (B.-Exner, 2019)

Suppose that $\pi R_0^2 = |\Omega|$ and denote by B the disk of radius R_0 and center in the origin, then

$$\lambda_{1,\Omega}^{\omega}(x_0,y_0) \leq \lambda_{1,B}^{\omega}(0,0) + \left(\int_0^{2\pi} \left(rac{R'(arphi)}{R(arphi)}
ight)^2 \mathrm{d}arphi
ight) \sup_{0\leq m\leq rac{R_0^2\omega+\sqrt{R_0^4\omega^2+4j_{0,1}^2}}{2}} rac{j_{m,1}^2-m^2}{2\pi R_0^2}.$$

For large values of ω the right-hand -side behaves as

$$\lambda_{1,B}^{\omega}(0,0) + \mathcal{O}ig(R_0^{2/3} \omega^{4/3} ig)
ightarrow -\infty \quad \textit{as} \quad \omega
ightarrow \infty$$

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D. Barseghyan, P. Exner, Spectral geometry in a rotating frame: properties of the ground state, arXiv:1902.03038 [math.SP]

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Thank you for your attention

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Diana Barseghyan 23/23