



Discretization of the double curl equation by discrete differential forms and collocation techniques

Stefan Kurz Universität der Bundeswehr, Hamburg

Oliver Rain Robert Bosch GmbH, Stuttgart,



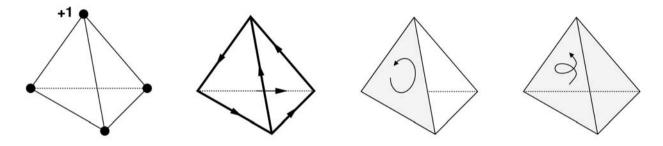


- Introduction to discrete forms
- Boundary Value Problems, Discretization of Cauchy data
- Adaptive Cross Approximation of BEM matrices
- Numerical Examples





• The elements of $S_p(\Omega_h)$ are called *p*-facets.



- A *p*-chain is a weighted sum of *p*-facets: $\Omega_h^p = \sum_{s_i \in S_p(\Omega_h)} \gamma_i s_i, \ \gamma_i \in \mathbb{R}$, represented by a vector $\{\Omega_h^p\} = (\gamma_1, \dots, \gamma_{k_p})^T$.
- Integration over a *p*-chain: $\omega \mid \Omega_h^p = \sum_{i=1}^{k_p} \gamma_i (\omega \mid s_i) = \sum_{i=1}^{k_p} \gamma_i \omega_i$
- *p*-cochain $\{\omega\} = (\omega_1, \ldots, \omega_{k_p})^T$ represents a discrete DF on mesh Ω_h .





• *p*-forms assign to any *p*-dimensional manifold Ω^p a real number

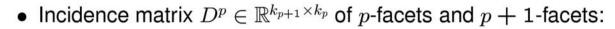
$$\omega \mid \Omega^p := \int_{\Omega}^p \omega$$

• Discrete *p*-forms assign to any *p*-chain Ω_h^p a real number

$$\omega_h \mid \Omega_h^p \; = \; \sum_{i=1}^{k_p} \gamma_i \, \omega_i$$

- Discretization: 0-form $\{\omega\} = (\omega \mid n_i)_{i=1}^{k_0}$ nodal values 1-form $\{\omega\} = (\omega \mid e_i)_{i=1}^{k_1}$ circulation across the edges 2-form $\{\omega\} = (\omega \mid f_i)_{i=1}^{k_2}$ flux through the faces 3-form $\{\omega\} = (\omega \mid t_i)_{i=1}^{k_3}$ cell values
- Denote the vector space of *p*-cochains on Ω_h by $\mathcal{C}^p(\Omega_h)$.





$$D_{i,j}^p = \begin{cases} 0, & \text{facet } s_j^p \text{ is not a subset of the boundary of facet } s_i^l \\ \pm 1, & \text{facet } s_j^p \text{ is a subset of the boundary of facet } s_i^{p+1} \\ & \text{with orientation} \pm 1. \end{cases}$$

• Discrete representation of the boundary

 $\{\partial \Omega_h^{p+1}\} = [D^p]^T \{\Omega_h^p\}$

• Discretization of the outer derivative

$$\{d\omega\} \mid \{\Omega\} = \{\omega\} \mid \{\partial\Omega\}$$
 (discrete Stokes' theorem)
$$= \{\omega\} \mid [D^p]^T \{\Omega\}$$

$$= [D^p] \{\omega\} \mid \{\Omega\}$$

$$\Rightarrow \quad \{\mathsf{d}\omega\} = [D^p]\{\omega\}$$

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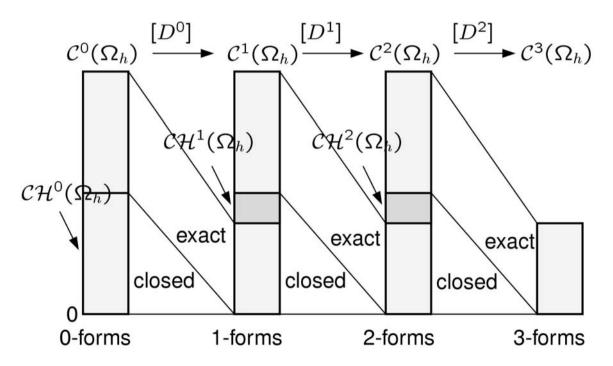
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• There are finite-dim. spaces $\mathcal{HC}^p(\Omega_h) \subset \mathcal{C}^p(\Omega_h)$: for $\{\omega\} \in \mathcal{C}^p(\Omega_h)$ holds:

$$[D^{p}]\{\omega\} = 0 \iff \exists \{\eta\} \in \mathcal{C}^{p-1}(\Omega_{h}), \ \{\gamma\} \in \mathcal{HC}^{p}(\Omega_{h})$$

satisfying $\{\omega\} = [D^{p-1}]\{\eta\} + \{\gamma\}.$



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- Cochains are **representatives** of discrete forms. Interpolation of *p*-cochains with Whitney *p*-forms yields discrete *p*-forms.
- Whitney *p*-form of a *p*-facet s_i of a tetrahedral mesh:

$$eta_{s_i}^p = p \sum_{j=0}^p (-1)^j \lambda_{n_j} \mathrm{d} \lambda_{n_0} \wedge \cdots \wedge \mathrm{d} \lambda_{n_{j-1}} \wedge \mathrm{d} \lambda_{n_{j+1}} \wedge \cdots \wedge \mathrm{d} \lambda_{n_p},$$

where λ_{n_j} is the linear nodal ansatz function of the node n_j .

• Interpolation $\{\beta^p\}$: $C^p(\Omega_h) \longrightarrow W^p(\Omega_h)$

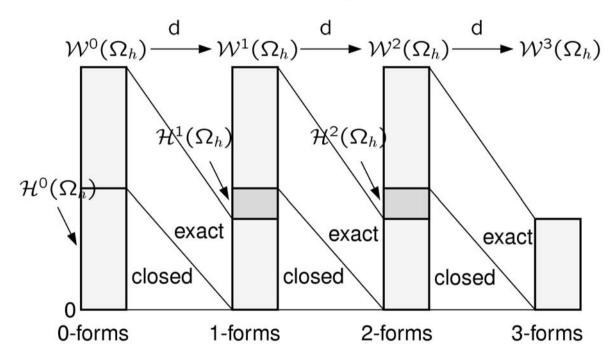
$$\omega_h = \sum_{i=1}^{k_p} \omega_i \ \beta_{s_i}^p =: \{\omega\}^T \{\beta^p\}$$

 $\mathcal{W}^p(\Omega_h)$ is the vector space of discrete *p*-forms.





• DeRham complex is invariant w.r.t. interpolation







The discrete Dirichlet problem reads:
 For β ∈ W¹(Γ_h) find γ ∈ W¹(d₀, Γ_h) such that

$$\mathcal{V}\gamma \mid \Gamma_{h}^{1} = \left(rac{\Theta}{4\pi}\mathcal{I} + \mathcal{K}
ight)eta \mid \Gamma_{h}^{1}, \ orall \Gamma_{h}^{1} \in \mathcal{C}_{1}(\partial_{0},\Gamma_{h})$$

From DeRham theorem follows

 $\mathcal{W}^1(\mathsf{d}_0, \Gamma_h) = \mathsf{d}\mathcal{W}^0(\Gamma_h) \oplus \mathcal{H}^1(\Gamma_h)$

- Discretization of W⁰(Γ_h): nodal ansatz functions
 Discretization of H¹(Γ_h): cycles [R.Hiptmair and J.Ostrowski, 2001]
- Assume in the sequel trivial topology $\mathcal{W}^1(d_0, \Gamma_h) = d\mathcal{W}^0(\Gamma_h)$
- Collocation on boundaries of dual faces





• The discrete Neumann problem reads: For $\gamma \in W^1(d_0, \Gamma_h)$ find $\beta \in W^1(\Gamma_h)$ such that

$$\mathcal{V} \gamma \mid \Gamma_h^1 = \left(rac{\Theta}{4\pi}\mathcal{I} + \mathcal{K}
ight) oldsymbol{eta} \mid \Gamma_h^1, \ orall \Gamma_h^1 \in \mathcal{C}_1(\Gamma_h)$$

- Discretization of $\mathcal{W}^1(\Gamma_h)$: edge ansatz functions
- Collocation on primal edges



• Single layer potential \mathcal{V} , double layer potential \mathcal{K} :

$$\mathcal{V} \boldsymbol{\gamma} = \int_{\Gamma} (\gamma_D \mathbf{G}) \wedge \boldsymbol{\gamma}, \quad \mathcal{K} \boldsymbol{\beta} = \int_{\Gamma} (\gamma_N \mathbf{G}) \wedge \boldsymbol{\beta}$$

 $\boldsymbol{\gamma} \approx \sum_{i=1}^N \gamma_i \operatorname{\mathbf{curl}}_{\Gamma} \phi_i, \quad \boldsymbol{\beta} \approx \sum_{i=1}^E \beta_i \boldsymbol{\omega}_i$

• Entries of the matrices

$$V_{ij} = \int_{C_i} \langle \int_{\Gamma_h} \mathbf{G}(\mathbf{x}, \mathbf{y}) \operatorname{curl}_{\Gamma} \phi_j(\mathbf{x}) dF_x, dl_y \rangle,$$

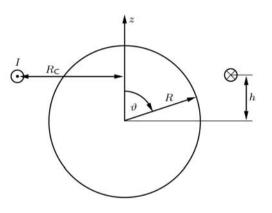
$$K_{ij} = \int_{C_i} \langle \int_{\Gamma_h} (\operatorname{curl}_x \mathbf{G}(\mathbf{x}, \mathbf{y}) \times \mathbf{n}(\mathbf{x}))^T \omega_j(\mathbf{x}) dF_x, dl_y \rangle,$$

where C_i are collocation contours.

- Dirichlet problem: $V \in \mathbb{R}^{N \times N}$, $K \in \mathbb{R}^{N \times E}$ Neumann problem: $V \in \mathbb{R}^{E \times N}$, $K \in \mathbb{R}^{E \times E}$
- Analytic inner integration for triangular and rectangular meshes.



• Sphere with Radius R = 0.05m immersed in the field of a current I = 20kA in a circular coil, $R_C = 0.07$ m, h = 0.03m. [Z.Rhen]



• Vector potential for the exterior domain can be written analytically:

$$\alpha(r,\theta) = \alpha_{\mathsf{S}}(r,\theta) - \frac{R}{r} \alpha_{\mathsf{S}}(\frac{R^2}{r},\theta), \ r \ge R,$$

where $\alpha_{S} = \int_{\Omega^{C}} \mathbf{G} \wedge \eta$ is the source potential due to the coil's excitation.

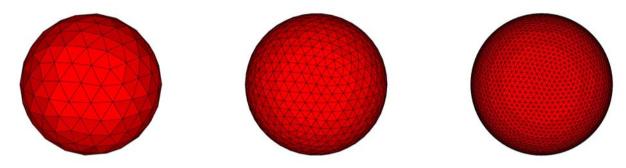
• The corresponding Neumann data γ can be calculated analytically.

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• Three meshes of the sphere are considered

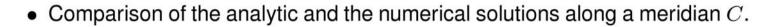


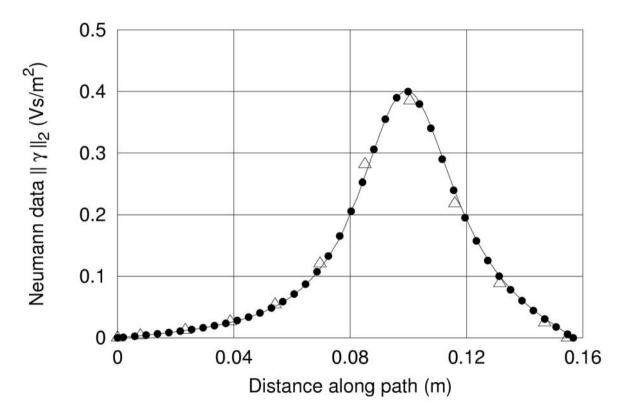
Mesh	Coarse	Medium	Fine
# Nodes	162	642	2562
# Edges	480	1920	7680
# Trias	320	1280	5120
cond(V)	4.40	8.93	18.16
ε	8.36%	3.55%	1.62%

$$\varepsilon = \max_{\mathbf{x} \in C} \ \frac{\|\boldsymbol{\gamma}_{\text{ana}}(\mathbf{x}) - \boldsymbol{\gamma}_{\text{num}}(\mathbf{x})\|_2}{\|\boldsymbol{\gamma}_{\text{ana}}(\mathbf{x})\|_2}$$

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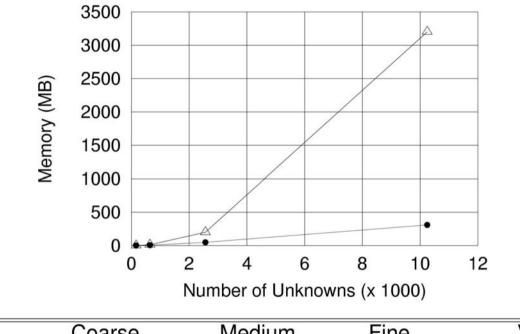
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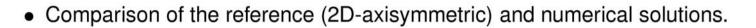
• ACA compression of the BEM matrices (Accuracy $\varepsilon = 10^{-3}$)

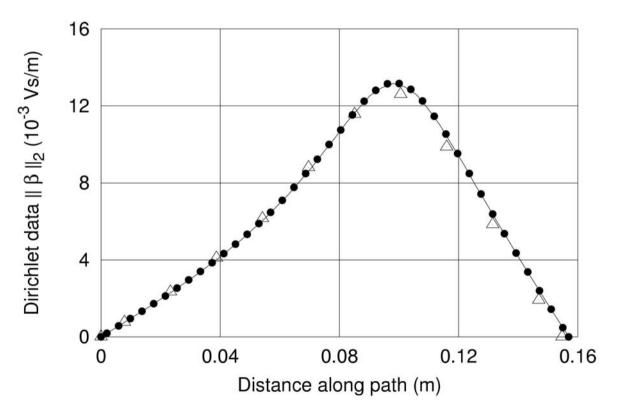


Mesh	Coarse	Medium	Fine	Very fine
Rel. size (V)	93.7%	63.3%	35.4%	14.0%
Rel. size(K)	85.3%	43.9%	20.7%	8.2%

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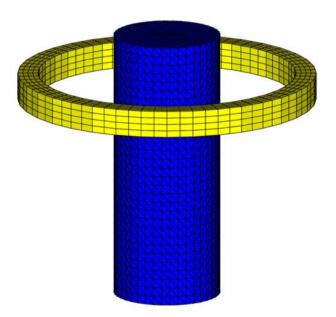


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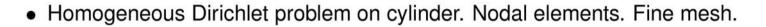


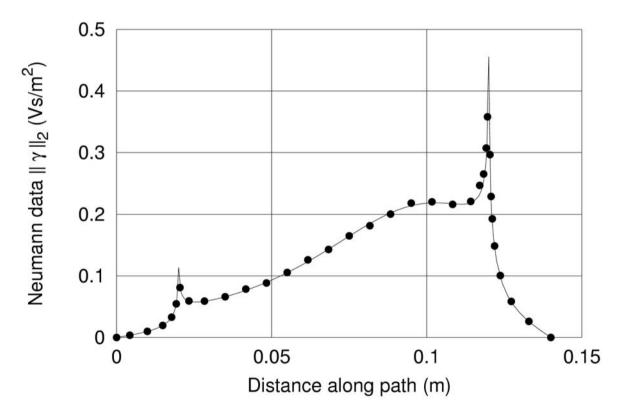


• Cylinder immerced in the field of a circular coil



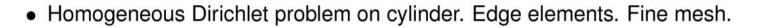


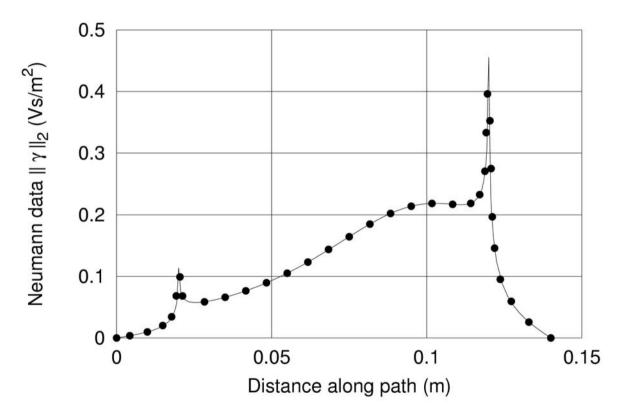




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- Discrete DFs provide a natural discretization of differential forms.
- DeRham theorem is identical for DFs, cohains and discrete DFs.
- Generalization of the point collocation technique by DeRham maps.
- BEM matrices for triangular and rectangular meshes can be computed semianalytically
- Due to the asymptotically smooth kernels BEM matrices can be compressed by the ACA.
- Numerical tests show a good approximation of the analytic solution (Dirichlet problem) and the reference 2D-axisymmetric solution (Neumann problem) on the sphere.
- On a cylinder edge elements achieve a better approximation of the reference solution, especially for the singular solution.