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Some properties of probability generating functions:

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The loss function is then given by $L = \sum_{i=1}^{n} \bar{X}_i v_i L_0 \approx \sum_{i=1}^{n} X_i v_i L_0$, where \bar{X}_i is the loss indicator and (X_1, \ldots, X_n) has a PMD with factor vector (Z_1, Z_2, \ldots, Z_m) as described above.

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Then $g_N(t) = \int_0^\infty \dots \int_0^\infty g_{N|Z=(z_1,z_2,\dots,z_m)} f_1(z_1) \dots f_m(z_m) dz_1 \dots dz_m =$

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Analogous computations as in the case of $g_N(t)$ yield:

$$g_L(t) = \prod_{i=1}^m \left(\frac{1-\delta_j}{1-\delta_j \Lambda_j(t)}
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$$g_N^{(k)}(0) = \sum_{l=0}^{k-1} \binom{k-1}{l} g_N^{(k-1-l)}(0) \sum_{j=1}^m l! \alpha_j \delta_j^{l+1}$$
, where $k>1$.