06. Initial and final topology

We consider the following problem:

Given a set (!) X and a family (Y_i, σ_i) of spaces and corresponding functions $f_i : X \to Y_i$, $i \in I$.

Find a topology τ on X such that all functions $f_i: (X, \tau) \to (Y_i, \sigma_i)$ become continuous.

It is obvious that the discrete topology on X fulfills the requirement. Therefore we look for the possibly coarsest topology on X that fulfills the requirement.

Since continuity means that the inverse images of open sets are open, we consider the family

 $\mathcal{S} = \{ f_i^{-1}(V_i) : V_i \text{ open in } Y_i, i \in I \}$

From a previous discussion we know that there is a unique topology τ on X having S as a subbase, and that it is the coarsest topology making all sets of S open.

Definition. τ is called the **initial topology** on X with respect to the functions $f: X \to Y_i$, $i \in I$.

Remarks.

1) Let X be a set and (Y, σ) a space and $f: X \to Y$.

Then the initial topology τ on X with respect to f is

$$au = \{ f^{-1}(V) : V \in \sigma \}$$

2) Let $(X, \|\cdot\|)$ be a normed space over \mathbb{K} . Then

 $X' = \{ f : X \to \mathbb{K} : f \text{ is linear and bounded} \}$

is called the dual space of X.

The initial topology on X with respect to all $f \in X'$ is called the **weak**

topology on X (it is, in general, coarser than the topology induced by the norm and not metrizable).

The initial topology has the following "universal property":

Let τ be the initial topology on X with respect to the family of functions $\{f_i: X \to (Y_i, \sigma)\}$, $i \in I\}$.

Let (Z, ρ) be a space and $g: Z \to X$ a function. Then

g is continuous $\Leftrightarrow f_i \circ g : Z \to Y_i$ is continuous $\forall i \in I$

Proof.

If g is continuous then $f_i \circ g$ is continuous for each $i \in I$ since each f_i is continuous.

Conversely, $\{f_i^{-1}(V_i) : V_i \text{ open in } Y_i, i \in I\}$ is a subbase of (X, τ) .

By assumption, each $g^{-1}(f_i^{-1}(V_i)) = (f_i \circ g)^{-1}(V_i)$ is open in Z.

Therefore, by a previous theorem, g is continuous. \Box

The subspace topology

Let (X, τ) be a space and $A \subseteq X$.

The initial topology on A with respect to the inclusion function $j: A \to X$ where $j(x) = x \quad \forall x \in A$, is called the **subspace topology** on A and denoted by $\tau|_A$.

Obviously, $\tau|_A = \{j^{-1}(O) = O \cap A : O \in \tau\}$.

 $(A,\tau|_A)$ is called a subspace of (X,τ) , and $~G\subseteq A~$ is called open in A~ if $~G\in\tau|_A$.

(So the sets open in A can be represented as an intersection of an open set in X and A.)

Example. Let $X = \mathbb{R}$ with the usual topology and A = [0, 2). Then $[0, 1) = (-1, 1) \cap A$ is open in A but not in X. The proof of the following result is left as an exercise.

Proposition. Let (X, τ) be a space and $A \subseteq X$.

1) $B \subseteq A$ is closed in $A \Leftrightarrow$

there exists $F \subseteq X$ closed in X such that $B = F \cap A$.

2) For $B \subseteq A$, the closure of B with respect to $(A, \tau|_A)$ is denoted by \overline{B}^A .

Then $\overline{B}^A = \overline{B} \cap A$.

However, we only have $\operatorname{int} B \cap A \subseteq \operatorname{int}_A B$ in general.

 $(\operatorname{int}_A B \text{ is the interior of } B \text{ with respect to } (A, \tau|_A))$.

3) Let (X,d) be a metric space and $A \subseteq X$.

Then A itself is a metric space by the induced metric $d|_{A \times A}$.

It holds that the topology on A generated by $d|_{A\times A}$ coincides with the subspace topology $\tau_d|_A$.

4) Let $B \subseteq A \subseteq X$.

If B is open (resp. closed) in X then B is open (resp. closed) in A.

If A is open in X and B is open in A then B is open in X.

If A is closed in X and B is closed in A then B is closed in X.

Definition. $A \subseteq X$ is called a **discrete subspace** of (X, τ) if $\tau|_A$ is the discrete topology on A.

Exercise. Show that \mathbb{R} with the usual topology has a countable discrete subspace but **not** an uncountable discrete subspace.

Show that the Niemitzky plane has an uncountable discrete subspace.

The product topology

For each $i \in I$ let (X_i, τ_i) be a space.

The **product set** $X = \prod_{i \in I} X_i$ is (by definition) the set of all functions $x: I \to \bigcup_{i \in I} X_i$ such that $x(j) \in X_j \quad \forall \ j \in I$.

(An element of the product set is obtained by "choosing" an element from each set X_i .)

We use the notation $x = (x_i)_{i \in I}$ or $x = (x_i)$ where $x_i = x(i)$.

 x_i is called the *i*th coordinate (or component) of x.

If I is finite, say $I = \{1, 2, ..., n\}$ we write $X = X_1 \times X_2 \times ... \times X_n$ and $x = (x_1, x_2, ..., x_n)$.

For each $i \in I$ there exists a canonical function, the *i*th projection

$$p_i: X = \prod_{i \in I} X_i \to X_i$$
 where $p_i(x) = x_i$.

Note that each p_i is surjective.

Definition. The initial topology on $X = \prod_{i \in I} X_i$ with respect to the family $\{p_i : i \in I\}$ is called the **product topology** τ on X.

Remark. According to previous results

1) Each p_i is continuous.

2) A function $f: Y \to \prod_{i \in I} X_i$ is continuous if and only if the "component functions" $p_i \circ f: Y \to X_i$ are continuous for each $i \in I$.

The function $f : \mathbb{R} \to \mathbb{R} \times \mathbb{R}$ with $f(t) = (\cos t, t^2)$ is continuous because the functions $f_1(t) = \cos t$ and $f_2(t) = t^2$ are continuous.

Definition. A function $f: (X, \tau) \to (Y, \sigma)$ between any spaces is an **open** function (resp. a **closed** function) if

 $\forall \ O \in \tau \ : \ f(O) \in \sigma$

(resp. $\forall A \text{ closed in } (X, \tau) : f(A) \text{ is closed in } (Y, \sigma)$)

Remark. (Proof as exercise)

Let \mathcal{B} be a base for (X, τ) . Then $f : (X, \tau) \to (Y, \sigma)$ is open if and only if $f(B) \in \sigma \quad \forall B \in \mathcal{B}$.

Let $X = \prod_{i \in I} X_i$ have the product topology τ .

Then $\mathcal{S} = \{p_i^{-1}(O_i) : i \in I \text{ and } O_i \subseteq X_i \text{ open in } X_i\}$ is subbase for (X, τ) .

Note that $p_i^{-1}(O_i) = \{x \in X : x_i \in O_i\}$.

A typical member of the resulting base for (X, τ) has the form

$$B = p_{i_1}^{-1}(O_{i_1}) \cap \ldots \cap p_{i_k}^{-1}(O_{i_k}) = \{ x \in X : x_{i_1} \in O_{i_1}, \ldots, x_{i_k} \in O_{i_k} \}$$

where $i_1, \ldots, i_k \in I$ and $O_{i_j} \subseteq X_{i_j}$ open in X_{i_j} .

(In the finite case $X = X_1 \times \ldots \times X_n$ we have

$$B = p_1^{-1}(O_1) \cap \ldots \cap p_n^{-1}(O_n) = O_1 \times \ldots \times O_n$$

Now let $B = p_{i_1}^{-1}(O_{i_1}) \cap \ldots \cap p_{i_k}^{-1}(O_{i_k})$ and $i \in I$.

If $i = i_j \in \{i_1, \ldots, i_k\}$ then $p_i(B) \subseteq O_i$. If $x_i \in O_i$ it is possible to "construct" an element $x \in B$ having x_i as its *i*th coordinate.

Therefore $p_i(B) = O_i$.

If $i \notin \{i_1, \ldots, i_k\}$ then, taking any $x_i \in X_i$, it is possible to "construct" an element $x \in B$ having x_i as its *i*th coordinate.

Therefore $p_i(B) = X_i$. Now we have

Proposition. Each projection $p_i: X \to X_i$ is an open function.

Remark. If $X_i = Y$ for each $i \in I$, we write for the product space $X = Y^I = \{x : I \to Y\}$.

Hence the set of all functions $x: \mathbb{R} \to \mathbb{R}$ can be written as the product set $\mathbb{R}^{\mathbb{R}}$.

The resulting product topology is called the **topology of pointwise con-vergence**.

Examples.

1) Consider $\mathbb{R}^n = \mathbb{R} \times \ldots \times \mathbb{R}$.

One the one hand we have the topology generated by the metric on \mathbb{R}^n , and on the other hand we have the product topology (where \mathbb{R} has the usual topology).

Those two topologies coincide!

(Hint for the proof in the case n = 2: each open ball contains an open square and conversely)

2) For each $i \in I$ let τ_i be the discrete topology on X_i .

Then the product topology τ is discrete if and only if I is finite.

Proof. Let I be finite, i.e. $X = X_1 \times \ldots \times X_n$.

Then $\{x\} = \{x_1\} \times \ldots \times \{x_n\}$ is open in X for $x = (x_1, \ldots, x_n)$.

Conversely, suppose that $\ I \$ is infinite and assume that $\ \{x\} \in \tau \$ for $x \in X$.

Then there exist $i_1, \ldots, i_k \in I$ and corresponding open sets O_{i_1}, \ldots, O_{i_k} such that

 $\{x\} = p_{i_1}^{-1}(O_{i_1}) \cap \ldots \cap p_{i_k}^{-1}(O_{i_k})$

It is possible to choose $j \notin \{i_1, \ldots, i_k\}$ and $y_j \in X_j$ with $y_j \neq x_j$. "Construct" $y \in X$ with the y_j and $y_i = x_i$ for $i \neq j$.

Then
$$y \neq x$$
 but $y \in p_{i_1}^{-1}(O_{i_1}) \cap \ldots \cap p_{i_k}^{-1}(O_{i_k})$, a contradiction. \Box

3) For each $n \in \mathbb{N}$ let $X_n = \{0, 1\}$ have the discrete topology.

Then $X = \prod_{n \in \mathbb{N}} X_n = \{0, 1\}^{\mathbb{N}}$ consists of all sequences containing only 0 or 1.

This space is called the **Cantor cube**.

We now consider a related problem than the previous one.

Given a set (!) Y and a family (X_i, τ_i) of spaces and corresponding functions $f_i : X_i \to Y$, $i \in I$.

Find a topology σ on Y such that all functions $f_i : (X_i, \tau_i) \to (Y, \sigma)$ become continuous.

It is obvious that the indiscrete topology on Y fulfills the requirement. Therefore we look for the possibly finest topology on Y that fulfills the requirement.

It is easily checked that

 $\sigma = \{ V \subseteq Y : f_i^{-1}(V) \in \tau_i \quad \forall \ i \in I \}$

is, in fact, a topology, and also the finest topology on Y such that all $f_i: X_i \to Y$ are continuous.

 σ is called the **final topology** on Y with respect to the functions $f_i: X_i \to Y$, $i \in I$.

Remark. Also the final topology has a "universal property".

If $g: Y \to Z$ is a mapping then g is continuous if and only $g \circ f_i : X_i \to Z$ is continuous for each $i \in I$.

Proof. If g is continuous then clearly all functions $g \circ f_i$, $i \in I$ are continuous.

Conversely, suppose that all $g \circ f_i$ are continuous. Let $W \subseteq Z$ be open in Z and let $V = g^{-1}(W) \subseteq Y$.

Since $f_i^{-1}(V) = f_i^{-1}(g^{-1}(W)) = (g \circ f_i)^{-1}(W) \in \tau_i$ for each $i \in I$ it follows that $V \in \sigma$ and that g is continuous. \Box

The sum topology

Let (X_i, τ_i) , $i \in I$ be a family of spaces such that $X_{i_1} \cap X_{i_2} = \emptyset$ whenever $i_1 \neq i_2$.

Consider $X = \bigcup_{i \in I} X_i$.

For each $i \in I$ we have the canonical inklusion $j_i : X_i \to X$ where $j_i(x) = x$ for each $x \in X_i$.

The final topology τ on X with respect to $\{j_i : i \in I\}$ is called the **sum topology**.

We also write $X = \bigoplus_{i \in I} X_i$ or $X = \sum_{i \in I} X_i$.

Let $i^* \in I$. Then for each $i \in I$ we have $j_i^{-1}(X_{i^*}) = X_{i^*}$ whenever $i = i^*$, and $j_i^{-1}(X_{i^*}) = \emptyset$ whenever $i \neq i^*$.

Consequently, each subset $X_i \subseteq X$ is open and closed in (X, τ) .

Furthermore, a subset $V \subseteq X$ is open in (X, τ) if and only if $V \cap X_i \in \tau_i \quad \forall i \in I$.

Remark. Sometimes it is desirable to consider sums of the same spaces, for example $\mathbb{R} \oplus \mathbb{R}$.

In such a case we can construct the sum of the spaces $X_1 = \mathbb{R} \times \{1\}$ and $X_2 = \mathbb{R} \times \{2\}$.

The quotient topology

Let (X, τ) be a space and " ~ " be an equivalence relation X.

Then the set of all (different) equivalence classes is denoted by

 $X/_{\sim} = \{ [x] : x \in X \}$ where $[x] = \{ y \in X : y \sim x \}$.

We have also a canonical surjective function $\pi: X \to X/_{\sim}$ defined by $\pi(x) = [x]$.

The final topology σ on $X/_{\sim}$ with respect to the function π is called the **quotient topology**.

 $(X/_{\sim}, \sigma)$ is called **quotient space**.

Clearly, $\sigma = \{ W \subseteq X/_{\sim} : \pi^{-1}(W) \in \tau \}$.

Examples.

1) Let $X = [0, 1] \subseteq \mathbb{R}$ have the usual topology.

Only 0 and 1 are equivalent to each other and, of course, each point is equivalent to itself.





We obtain, at least "geometrically", $X/_{\sim} \simeq S^1$ where

$$S^n = \{ x \in \mathbb{R}^{n+1} : \sum_{i=1}^{n+1} x_i^2 = 1 \}$$

is the n-dimensional sphere .

2) Let $X = \mathbb{R}^2$ have the usual topology and

 $(x_1, y_1) \sim (x_2, y_2) \quad \Leftrightarrow \quad x_1 - x_2 \in \mathbb{Z} \quad \text{and} \quad y_1 - y_2 \in \mathbb{Z}$

An equivalence class is a lattice of points in the plane. One can show that

 $\mathbb{R}^2/_{\sim} \simeq S^1 \times S^1$

for which a geometrical interpretation is the 2-dimensional Torus.

3) Let $X = [0,1] \times [0,1]$ be the unit square.

If we "identify" all points of the boundary then $X/_{\sim}$ can be interpreted geometrically as the surface of the sphere S^2 .

In a similar way one can obtain the surface of a cylinder and the Moebius strip.

Equivalence relations can be obtained by functions.

Let $\,f:(X,\tau)\to (Y,\sigma)\,$ be a function. Then there is a natural equivalence relation on $\,X$, namely

 $x_1 \sim x_2 \quad \Leftrightarrow \quad f(x_1) = f(x_2)$

We observe also that the function

$$\widehat{f}: X/_{\sim} \to Y \quad , \quad \widehat{f}([x]) = f(x)$$

is well-defined (!), therefore the diagram



is commutative, i.e. $f = \widehat{f} \circ \pi$.

By a previous result, f is continuous if and only if \hat{f} is continuous. Furthermore, f is surjective if and only if \hat{f} is surjective.

Next we observe that \hat{f} is injective:

 $\widehat{f}([x_1]) = \widehat{f}([x_2]) \Rightarrow f(x_1) = f(x_2) \Rightarrow x_1 \sim x_2 \Rightarrow [x_1] = [x_2]$

Hence: If f is surjective and continuous, then \hat{f} is bijective and continuous.

However, the inverse function $(\widehat{f})^{-1}: Y \to X/_{\sim}$ need not be continuous in general (i.e. Y and $X/_{\sim}$ need not be homeomorphic).

Proposition. If f is surjective, continuous and, in addition, an open function (or a closed function) then $(\widehat{f})^{-1}$ is continuous.

Proof. (For the case that f is an open function) First observe that $\widehat{f}(W) = f(\pi^{-1}(W))$ for $W \subseteq X/_{\sim}$. If $W \subseteq X/_{\sim}$ is open then $\pi^{-1}(W) \subseteq X$ is open.

Since f is an open function, $f(\pi^{-1}(W)) = \widehat{f}(W) \subseteq Y$ is open.

Therefore \hat{f} is an open function.

But this means that $(\widehat{f})^{-1}: Y \to X/_{\sim}$ must be continuous because $((\widehat{f})^{-1})^{-1}(W) = \widehat{f}(W)$ (i.e. the inverse image of an open set in $X/_{\sim}$ under the function $(\widehat{f})^{-1}$ is open in Y).

Example. Consider $f: [0,1] \to S^1 \subseteq \mathbb{R}^2$, $f(t) = (\cos 2\pi t, \sin 2\pi t)$.

Then f is surjective and continuous.

We will see later that f is a closed function.

Thus \widehat{f} is bijective and continuous **and** $(\widehat{f})^{-1}$ is continuous.

Observe that $f(t_1) = f(t_2) \iff t_1 = 0, t_2 = 1$ or $t_1 = 1, t_2 = 0$.